Numerical Modeling of Contaminant Transport with Spatially-Dependent Dispersion and Non-Linear Chemical Reaction

A. J. Chamkha

Manufacturing Engineering Department
The Public Authority for Applied Education and Training
P. O. Box 42325, Shuweikh, 70654 Kuwait
achamkha@yahoo.com

Received: 27.11.2006 **Revised:** 05.01.2007 **Published online:** 31.08.2007

Abstract. A one-dimensional advective-dispersive contaminant transport model with scale-dependent dispersion coefficient in the presence of a nonlinear chemical reaction of arbitrary order is considered. Two types of variations of the dispersion coefficient with the downstream distance are considered. The first type assumes that the dispersivity increases as a polynomial function with distance while the other assumes an exponentiallyincreasing function. Since the general problem is nonlinear and possesses no analytical solutions, a numerical solution based on an efficient implicit iterative tri-diagonal finitedifference method is obtained. Comparisons with previously published analytical and numerical solutions for special cases of the main transport equation are performed and found to be in excellent agreement. A parametric study of all physical parameters is conducted and the results are presented graphically to illustrate interesting features of the solutions. It is found that the chemical reaction order and rate coefficient have significant effects on the contaminant concentration profiles. Furthermore, the scale-dependent polynomial type dispersion coefficient is predicted to obtain significant changes in the contaminant concentration at all dimensionless time stages compared with the constant dispersion case. However, relatively smaller changes in the concentration level are predicted for the exponentially-increasing dispersion coefficient.

Keywords: contaminant transport, scale-dependent dispersion, numerical solution, nonlinear chemical reaction, finite-difference method.

Nomenclature

- a, b constants used in exponential dispersion coefficient
- c concentration of contaminant [ML⁻³]
- c_0 boundary concentration source [ML⁻³]
- C dimensionless concentration of contaminant
- D hydrodynamic dispersion coefficient [L²T⁻¹]
- D_e molecular diffusion coefficient [L²T⁻¹]

```
characteristic dispersion constant [L^2T^{-1}]
D_0
D^*
       dimensionless hydrodynamic dispersion coefficient
erf
       error function
erfc
       complementary error function
H
       unit step function
       chemical reaction rate coefficient of contaminant [T^{-1}(ML^{-3})^{1-n}]
k
       chemical reaction order
n_1, N
       constant used in polynomial dispersion coefficient
Pe
       Peclet number
       time [T]
t
       flow velocity [LT^{-1}]
u
       longitudinal distance [L]
\boldsymbol{x}
       characteristic longitudinal distance [L]
```

Greek symbols

- α dispersivity [L]
- η dimensionless longitudinal distance
- λ dimensionless chemical reaction rate coefficient
- au dimensionless time

1 Introduction

The problem of contaminant transport in soil, groundwater and surface water has been a research subject of many recent and old theoretical and experimental investigations. This is due to increased public awareness of significant contamination of groundwater and surface water by industrial, municipal, agricultural chemicals, accidental spills and effect of soil contamination resulting from landfills and burying of hazardous materials. The principle differential equation governing solute transport and chemical reactions has been developed using mass balance and advective-dispersive principles [1] and is widely used in modeling solute transport phenomenon. A number of analytical solutions for steady-state flow and different boundary and initial conditions were given by van Genuchten and Alves [2] for problems with linear adsorption and zero- and first-order production and decay. Analytical solutions play an important role in modeling because they offer fundamental insight into governing physical processes, provide useful tools for validating numerical approaches, and are sometimes more computationally efficient [3]. Most previously published analytical solutions to advective-dispersive transport problems are obtained based on the assumption of a homogeneous porous medium [2]. In reality, subsurface porous media through which the contaminant moves are seldom homogeneous and significant spatial variability of transport properties should be expected [3–5].

As a result of the heterogeneity of the porous media, the dispersion coefficients in all directions vary with the space coordinate and the resulting contaminant transport equation contains spatially-dependent coefficients. Limited analytical solutions for scale-dependent dispersion coefficients have been reported in the literature. Yates [6,7] obtained

one-dimensional solutions for uniform flow with constant concentration or constant concentration flux boundary conditions when the medium has a linearly or exponentially-increasing dispersion coefficient with the spatial coordinate. Huang et al. [8] also presented analytical solutions for a scale-dependent dispersion coefficient which increases linearly with the distance until some distance after which it reaches an asymptotic value. Logan [9] derived an analytical solution for the one-dimensional equations incorporating rate-limited sorption and first-order decay under time-varying boundary conditions, assuming an exponentially-increasing dispersion coefficient. Zi-ting [10] reported an analytical solution for an exponential-type dispersion process. However, the solutions given by Yates [6,7], Huang et al. [8], Logan [9] and Zi-ting [10] are complex and difficult to evaluate numerically. It is worth noting that other studies of solute transport employ time-dependent coefficients. Warrick et al. [11], Barry and Sposito [12] and Basha and El-Habel [13] reported analytical solutions to the one-dimensional advection-dispersion equation with arbitrary time-dependent dispersion and velocity coefficients.

This paper presents numerical solutions for one-dimensional contaminant transport through a semi-infinite porous medium domain in the presence of a nonlinear chemical reaction. The transport starts from a continuous contaminant source and the mechanical dispersion effect is assumed to vary with the downstream distance. The solutions include first- and second-order homogeneous irreversible chemical reactions as well as polynomial and exponentially-increasing spatially-dependent dispersion coefficients.

2 Formulation

Consider transient one-dimensional advective-dispersive contaminant transport in a porous medium from a continuous source with a non-linear chemical reaction. The movement of the contaminant takes place in the semi-infinite region $0 \le x < \infty$ and the dispersion coefficient is assumed to be spatially-dependent. The governing equation for this situation can be written as:

$$\frac{\partial c(x,t)}{\partial t} + u \frac{\partial c(x,t)}{\partial x} = \frac{\partial}{\partial x} \left(D(x) \frac{\partial c(x,t)}{\partial x} \right) - kc(x,t)^n, \tag{1}$$

where t is time, x is the one-dimensional spatial coordinate $(0 \le x < \infty)$ (or longitudinal distance), c(x,t) is the concentration, u is the uniform velocity, D(x) is the spatially variable hydrodynamic dispersion coefficient representing the sum of both the effects of molecular diffusion (D_e) and mechanical dispersion (αu) where α is usually called the dispersivity), k is the chemical reaction rate coefficient and n is the order of the homogeneous irreversible chemical reaction. It should be noted that the first term on the left hand side of equation (1) represents the transient or accumulation effect. The second term on the left hand side of the equation represents the advection or convection effect which is defined as the transport of contaminant by the mean velocity in the flow stream. The first term on the right side of the equation accounts for the dispersion or diffusion effect which is responsible for the spreading of the contaminant in the medium. The last term of equation (1) represents the nonlinear reaction effect which may take place

(depending on the nature and properties of the contaminant) between the contaminant and the medium.

The initial and boundary conditions for this problem are

$$c(x,0) = 0$$
, $c(0,t) = c_0$, $c(\infty,t) = 0$ or $\frac{\partial c(\infty,t)}{\partial x} = 0$, (2)

where c_0 represents a constant continuous concentration source.

Equation (1) can be written as

$$\frac{\partial c(x,t)}{\partial t} + u \frac{\partial c(x,t)}{\partial x} = D(x) \frac{\partial^2 c(x,t)}{\partial x^2} + \frac{\partial D(x)}{\partial x} \frac{\partial c(x,t)}{\partial x} - kc(x,t)^n.$$
 (3)

It is convenient to work with dimensionless equations. This can be accomplished by using

$$\eta = \frac{x}{x_0}, \quad \tau = \frac{ut}{x_0},
C(\eta, \tau) = \frac{c(x, t)}{c_0}, \quad D^*(\eta) = \frac{D(x)}{D_0},$$
(4)

where x_0 and D_0 are characteristic longitudinal distance and dispersion constant, respectively.

Substituting equation (4) into equations (3) and (2) gives, respectively

$$\frac{\partial C(\eta,\tau)}{\partial \tau} + \frac{\partial C(\eta,\tau)}{\partial \eta} = \frac{D^*(\eta)}{Pe} \frac{\partial^2 C(\eta,\tau)}{\partial \eta^2} + \frac{1}{Pe} \frac{\partial D^*(\eta)}{\partial \eta} \frac{\partial C(\eta,\tau)}{\partial \eta} - \lambda C(\eta,\tau)^n, \quad (5)$$

$$C(\eta, 0) = 0$$
, $C(0, \tau) = 1$, $C(\infty, \tau) = 0$ or $\frac{\partial C(\infty, \tau)}{\partial \eta} = 0$, (6)

where

$$Pe = \frac{ux_0}{D_0}, \quad \lambda = \frac{kx_0c_0^{n-1}}{u}$$
 (7)

are the Peclet number and dimensionless chemical reaction rate constant, respectively.

3 Numerical method

In its most general form, equation (5) is nonlinear. Therefore, an analytical solution to this equation is unlikely and a numerical procedure is required. Many existing computer codes employ a finite-difference approach for the solution of transport equations. It is logical to investigate the applicability of this methodology to equation (5). In the present work, an implicit iterative tri-diagonal finite-difference method similar to that discussed by Blottner [14] is employed. A two-point backward difference quotient is used to represent the dimensionless time τ derivative and three-point central difference quotients are used

to represent the dimensionless space η derivatives. The computation starts at $\tau=0$ and marches forward in time. At each time, a system of non-linear algebraic equations must be solved to determine the η distributions of C. An iterative procedure is employed for this purpose. At each iteration, an equivalent linear system of algebraic equations (the linearization being effected by representing some quantities by their values from the previous iteration) must be solved. These equations have a tri-diagonal form and can be solved by the Potter's method variables which can be determined by a forward sweep in the h direction. Then the physical variables can be found from a corresponding backward sweep. This process avoids the need for matrix inversion. Iteration is continued until convergence is obtained at a given time. The procedure moves forward for the next time.

It is helpful to have some analytical solutions for special cases of equation (5) to use as standards of comparison for the numerical procedure.

4 Analytical solutions

Consider the special case where $D^*(\eta) = 1$ (constant dispersion) and n = 1 (first-order chemical reaction) for which equations (5) and (6) are simplified to read

$$\frac{\partial C(\eta, \tau)}{\partial \tau} + \frac{\partial C(\eta, \tau)}{\partial \eta} = \frac{1}{Pe} \frac{\partial^2 C(\eta, \tau)}{\partial \eta^2} - \lambda C(\eta, \tau), \tag{8}$$

$$C(\eta, 0) = 0$$
, $C(0, \tau) = 1$, $C(\infty, \tau) = 0$ or $\frac{\partial C(\infty, \tau)}{\partial \eta} = 0$. (9)

These equations are linear and can be solved analytically by the Laplace transformation methods. Without going into detail, the solution of the above initial-value problem can be shown to be

$$C(\eta, \tau) = \frac{1}{2} \left(\exp\left(\frac{Pe - \sqrt{Pe^2 + 4\lambda Pe}}{2} \eta\right) \operatorname{erfc}\left(\frac{\sqrt{Pe} \eta - \sqrt{Pe + 4\lambda \tau}}{2\sqrt{\tau}}\right) + \exp\left(\frac{Pe + \sqrt{Pe^2 + 4\lambda Pe}}{2} \eta\right) \operatorname{erfc}\left(\frac{\sqrt{Pe} \eta + \sqrt{Pe + 4\lambda \tau}}{2\sqrt{\tau}}\right) \right)$$
(10)

$$\operatorname{erfc}(\zeta) = 1 - \operatorname{erf}(\zeta) = \frac{2}{\sqrt{\pi}} \int_{\zeta}^{\infty} \exp(-\theta^2) d\theta,$$
 (11)

where erf and erfc are the error function and complimentary error function, respectively and θ is a dummy variable. It should be noted that equation (10) is consistent with and represents the dimensionless form of that reported earlier by van Genuchten and Alves [2].

As $Pe \to \infty$ (no diffusivity), equation (10) reduces to

$$C(\eta, \tau) = \exp(-\lambda \eta) H(\tau - \eta), \tag{12}$$

where H is the unit step function. For small amounts of diffusivity $(1/Pe \ll 1)$ the discontinuity exhibited by equation (12) at $\eta = \tau$ is replaced by a narrow continuous transition layer.

For the special case in which $\lambda=0$ (no chemical reaction), equation (8) becomes a simple convection-diffusion equation. Equations (10) and (12) are valid with $\lambda=0$. This leads to the respective results:

$$C(\eta, \tau) = \frac{1}{2} \left(\operatorname{erfc}\left(\frac{\sqrt{Pe}(\eta - \tau)}{2\sqrt{\tau}}\right) \exp(Pe\,\eta) \operatorname{erfc}\left(\frac{\sqrt{Pe}(\eta + \tau)}{2\sqrt{\tau}}\right) \right), \tag{13}$$

$$C(\eta, \tau) = H(\tau - \eta). \tag{14}$$

The accuracy of the numerical method discussed above is validated by direct comparisons with the analytical results given in equations (10) and (13). These comparisons are presented in Figs. 1 and 2, respectively. It is clear from these figures that excellent agreement between the numerical and analytical results exists at all presented dimensionless times for both Pe=1 and Pe=100 considered in these figures.

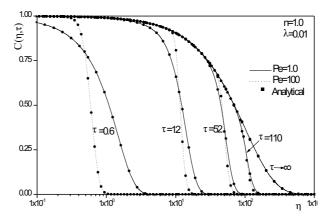


Fig. 1. Comparison between numerical and analytical solutions for concentration profiles.

In order to check the accuracy of the numerical results for a nonlinear chemical reaction, further comparisons are performed with the work of Onyejekwe [15] who reported the solution of a single-phase isothermal flow with nonlinear kinetics involving one reactant. The governing equation for this problem in an idealized one-dimensional finite region is given by the following transport equation and conditions:

$$\frac{\partial C(\eta,\tau)}{\partial \tau} + Pe \frac{\partial C(\eta,\tau)}{\partial \eta} = \frac{\partial^2 C(\eta,\tau)}{\partial \eta^2} - \lambda Pe C(\eta,\tau)^n, \tag{15}$$

$$C(\eta, 0) = 0, \quad \frac{\partial C(0, \tau)}{\partial \eta} - Pe C(0, \tau) = -Pe, \quad \frac{\partial C(1, \tau)}{\partial \eta} = 0.$$
 (16)

The initial-value problem given by equations (15) and (16) was solved numerically by the implicit finite-difference scheme discussed above. The obtained results for the exit concentration were compared with those reported by Dale [16], Ramachandran [17] and Onyejekwe [15] for different values of n, Pe and λ . These various comparisons are shown in Tables 1 through 3.

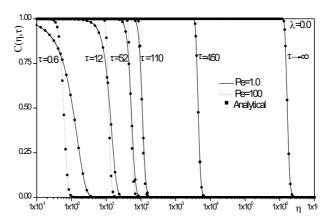


Fig. 2. Comparison between numerical and analytical solutions for concentration profiles.

Table 1. Comparison of numerical and approximate exit concentration for a single phase reactor with Dale (1969) and Onyejekwe (1997) with $\lambda=2.5$ and n=2

Pe	Dale	Onyejekwe	Present
	[16]	[15]	
1	0.4164	0.4164	0.41815
2	0.3882	0.3887	0.39058
3	0.3712	0.3707	0.37261
4	0.3587	0.3581	0.35994
10	0.3249	0.3239	0.32581

Table 2. Comparison of numerical and approximate exit concentration for a single phase reactor with Ramachandran (1990) and Onyejekwe (1997) with $\lambda=10$ and n=2

Pe	Ramachandran	Onyejekwe	Present
	[17]	[15]	
0.1	0.2604	0.2609	0.26164
1	0.2056	0.2056	0.20674
10	0.1209	0.1206	0.12082
100	0.0958	0.0957	0.09521
200	_	0.0836	0.09336
300	_	0.06341	0.09272
1000	0.0250	blows up	0.09181

Table 3. Comparison of numerical and approximate exit concentration for a single phase reactor with Onyejekwe (1997) with $\lambda=2.5$ and n=0.5

Pe	Onyejekwe	Present
	[15]	
1	0.5951	0.59968
2	0.5896	0.59179
4	0.5808	0.58299
10	0.5710	0.57363

Again, these comparisons show good agreement except for high values of Pe for which Onyejekwe's [15] method seem to under predict the exit concentration considerably and blows up for Pe=1000. These discrepancies are probably due to the inaccurate evaluation of the closed-form solutions who involve complicated functions reported by Onyejekwe's [15] for large values of Pe as evident from the fact that his solution blows up for Pe=1000. The various favorable comparisons reported in Figs. 1 and 2 and Tables 1 through 3 lend confidence in the numerical results to be reported in the next section.

5 Results and discussion

Numerical solutions for the general advective-dispersive-reactive contaminant transport equation (5) subject to the initial and boundary conditions (6) are obtained for two different types of scale-dependent dispersion coefficients. These are

$$D^*(\eta) = 1 + N\eta^{n_1},\tag{17}$$

$$D^*(\eta) = 1 - a \exp(-b\eta),\tag{18}$$

where all of N, n_1, a and b are dimensionless constants. It should be noted that when N=0 in equation (17) and a=0 in equation (18), the constant dispersion cases are recovered. It should be noted herein that Zoppou and Knight [18] derived an analytical solution for a transport problem with variable velocity and diffusivity. In the notation of this work, Zoppou and Knight [18] assumed that $D^*(\eta)=\eta^2$. Also, Zi-ting [10] used the exponential-type dispersion coefficient given by equation (18).

The computational domain was divided up into 500 points in the η direction and 600 points in the τ direction with variable step sizes in both directions. The initial step sizes and growth factors employed in the η and τ directions were 0.001, 0.001, 1.055 and 1.03, respectively. In this case, $\eta_{max} = 4 \times 1010$ represented the condition $\eta \to \infty$. These values were arrived at after performing various numerical experiments to access grid-independent results. The convergence criterion required that the difference between the current and previous iterations must be 10^{-7} .

Various numerical results are obtained and a representative set of results is presented in Figs. 3 through 12. These results are chosen to illustrate the influence of the chemical reaction order n, the Peclet number Pe, the chemical reaction constant λ , and the scale-

dependent dispersion constants n_1 and a. In Figs. 3 through 6, the dispersion coefficient is constant while in Figs. 7 through 12, the dispersion coefficient is spatially variable.

Fig. 3 presents the temporal development of the contaminant concentration profiles for various values of the chemical reaction order n (corresponding to first-, second- and third-order reactions) for the case of constant dispersion effects with Pe=1. In this and all subsequent figures, the space coordinate is represented by a logarithmic scale so as to capture the complete transition from unsteady conditions at small time values of the dimensionless time τ to steady-state conditions at $\tau=\infty$. In general, it is predicted that increases in the chemical reaction order increases the concentration. This is accompanied by an increase in the concentration boundary-layer thickness. The increase in the concentration field and its boundary layer appears to be more significant at larger time values especially at steady-state conditions. Physically, the increase in the concentration boundary-layer thickness as n increases means that it a solute transport with a first-order chemical reaction reaches its steady-state conditions at a faster rate than it would with a higher chemical reaction order.

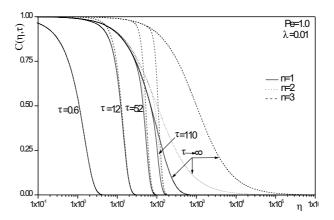


Fig. 3. Effects of reaction order on the temporal development of concentration profiles.

Fig. 4 displays the same parameters as in Fig. 3 except the value of the Peclet number which is set to 100 representing a small dispersive effect. The same general conclusion is obtained is which the contaminant concentration profile and its boundary-layer thickness tend to increase as n increases. Also, effect of increasing n is more pronounced at the steady-state conditions. However, by direct comparison with Fig. 3 for Pe=1, it can be seen that the effect of the chemical reaction order is more for contaminant transports with higher dispersive effects.

Fig. 5 illustrates the influence of the Peclet number Pe on the concentration profile for a contaminant transport with a second-order reaction at three different time values corresponding to early time ($\tau=0.6$), intermediate time ($\tau=52$) and state-state conditions ($\tau=\infty$). It is predicted that higher dispersive effects (low values of Pe) provide smoothing effects in the concentration profiles. Also, increasing the dispersive effects (that is, decreasing the values of Pe) has the tendency to increase the ability of the contaminant to

transport easier through the porous medium. This is reflected in the increases in the values of C as Pe decreases. In addition, as Pe decreases, the concentration boundary-layer thickness increases and this seems to be more pronounced at early transport time stages. It should also be noted that at early time stages ($\tau=0.6$), the concentration increases as Pe decreases every where except in the immediate vicinity of the inlet boundary ($\eta=0$). This is because as $Pe\to\infty$ (no dispersive effects), it is expected that the concentration profile to drop sharply (a step function) to the terminal condition as $\eta\to\infty$.

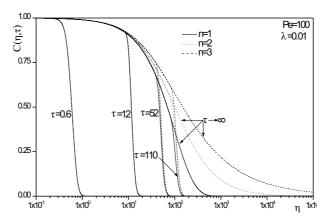


Fig. 4. Effects of reaction order on the temporal development of concentration profiles.

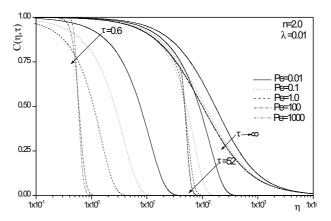


Fig. 5. Effects of Peclet number on the temporal development of concentration profiles.

Fig. 6 depicts the influence of the chemical reaction constant λ on the temporal development of the concentration profiles for a second-order reaction and Pe=1. Physically, the chemical reaction term in equation (5) represents a concentration decay or sink term. This means that for a specific reaction order, as λ increases, the decaying effect increases causing the contaminant concentration to decrease everywhere in the flow region away

from the boundaries and for all times except the early time stages. It is worth noting that the decaying effect is much more significant at the steady-state conditions than at all other time conditions. In addition, the concentration boundary-layer thickness decreases as λ increases.

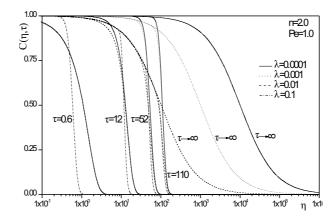


Fig. 6. Effects of reaction constant on the temporal development of concentration profiles.

Fig. 7 displays the effect of the dispersion coefficient power exponent n_1 for the polynomial-type dispersion coefficient on the temporal development of the contaminant concentration profiles for a first-order chemical reaction. In general, as the power exponent n_1 increases, the concentration level decreases everywhere except in the region close to the end boundary where it increases causing the concentration boundary-layer thickness to increase. This behavior takes place for almost all time stages. It should be noted that

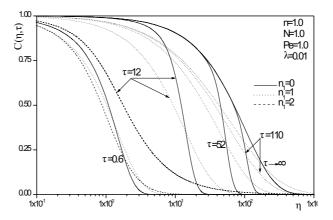


Fig. 7. Effects of dispersion exponent on the temporal development of concentration profiles.

for $n_1=2$, the steady-state condition is reached at a faster rate than that observed for the linear case where $n_1=1$. Specifically, for $n_1=2$ the steady-state conditions are achieved already at $\tau=12$.

Fig. 8 presents the same parameters as in Fig. 7 except for the value of n which is set to 2 representing a second-order chemical reaction. As is obvious from this figure, the same conclusion as in Fig. 7 is reached. That is, increasing the value of n_1 causes reductions in the contaminant concentration level everywhere except in the region close to the end boundary where it increases resulting in increases in the concentration boundary-layer thickness. Also, for $n_1=2$ the steady-state conditions are achieved at $\tau=12$.

Fig. 9 shows the effect of increasing n_1 on the contaminant concentration for a second-order chemical reaction and Pe=100. Again, in general, the concentration

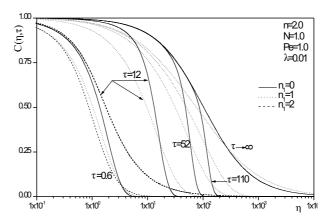


Fig. 8. Effects of dispersion exponent on the temporal development of concentration profiles.

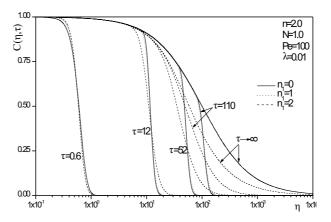


Fig. 9. Effects of dispersion exponent on the temporal development of concentration profiles.

level decreases in most of the domain except near the downstream boundary where it increases as n_1 increases. The changes in the concentration profiles are more prominent at the steady-state conditions than at the earlier time stages of the flow.

Figs. 10 through 12 present the effects of the constant of exponential-type dispersion coefficient a on the unsteady concentration profiles for the cases of first-order chemical reaction with Pe=1, second-order chemical reaction with Pe=1, and second-order chemical reaction with Pe=100, respectively. It is observed from these figures that increasing the value of the constant a causes decreases in the contaminant concentration level and in the concentration boundary layer thickness. Also, this decrease is greater at small time stages than it is at higher time stages. In addition, as expected, the effect of increasing the constant a is very little for high values of Pe (small dispersion effects). These trends are clearly depicted in Figs. 10 through 12.

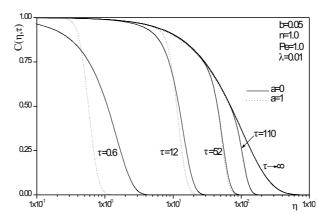


Fig. 10. Effects of exponential dispersion constant on the temporal development of concentration profiles.

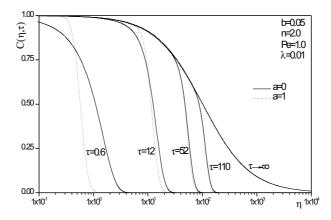


Fig. 11. Effects of exponential dispersion constant on the temporal development of concentration profiles.

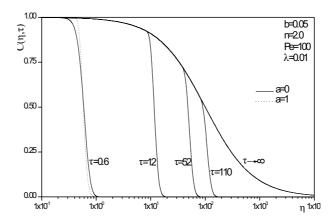


Fig. 12. Effects of exponential dispersion constant on the temporal development of concentration profiles.

6 Conclusion

A one-dimensional advective-dispersive contaminant transport model with scale-dependent dispersion coefficient in the presence of a nonlinear chemical reaction was considered. The scale-dependent dispersion coefficient was used to characterize dispersion in a heterogeneous porous medium. Two types of variations of the dispersion coefficient with the downstream distance were considered. The first type assumed that the dispersivity increased in a polynomial function with distance while the other assumed an exponentiallyincreasing function. The nonlinear chemical reaction assumed an arbitrary reaction order. Since the general problem was nonlinear and possessed no analytical solutions, a numerical solution based on an efficient implicit iterative tri-diagonal finite-difference method was obtained. The accuracy of the numerical method was validated by various favorable comparisons with known analytical solutions and reported numerical solutions for special cases of the main transport equation. Several numerical solutions based on the general model were reported assuming a uniform flow field. A parametric study was conducted and the results were presented graphically to illustrate interesting features of the solutions. It was found that the chemical reaction order and rate coefficient had significant effects on the contaminant concentration field especially at the steady-state conditions. It was predicted that as the chemical reaction order increased, the contaminant concentration increased. On the other hand, increases in the chemical reaction rate coefficient produced reductions in the contaminant concentration level. In addition, as the Peclet number was increased, the concentration level was decreased. Furthermore, the scale-dependent polynomial-type dispersion coefficient was predicted to obtain significant changes (reductions) in the contaminant concentration at all time stages compared with the constant dispersion case. However, relatively smaller changes (reductions) in the concentration level were predicted for the exponentially-increasing dispersion coefficient.

References

- 1. J. Bear, Dynamics of Fluid in Porous Media, Elsevier, New York, 1970.
- M. T. van Genuchten, W. J. Alves, Analytical solutions of the one-dimensional convectivedispersive solute transport equation, USDA Tech. Bull., 1661, 1982.
- C. Liu, W. P. Ball, J. H. Ellis, An analytical solution to the one-dimensional solute advectiondispersion equation in multi-layer porous media. *Transport in Porous Media*, 30, pp. 25–43, 1998.
- 4. L. W. Gelhar, Stochastic subsurface hydrology-from theory to applications, *Water Resources Research*, **22**, pp. 135S–145S, 1986.
- 5. G. Dagan, Time-dependent macrodispersion for solute transport in anisotropic heterogeneous aquifer, *Water Resources Research*, **24**, pp. 1491–1500, 1988.
- S. R. Yates, An analytical solution for one-dimensional transport in heterogeneous porous media, Water Resources Research, 26, pp. 2331–2338, 1990.
- 7. S. R. Yates, An analytical solution for one-dimensional transport in porous media with an exponential dispersion function, *Water Resources Research*, **28**, pp. 2149–2154, 1992.
- 8. K. Huang, M. T. van Genuchten, R. Zhang, Exact solutions for one-dimensional transport with asymptotic scale-dependent dispersion, *Appl. Math. Modell.*, **20**, pp. 298–308, 1996.
- 9. J. D. Logan, Solute transport in porous media with scale-dependent dispersion and periodic boundary conditions, *J. Hydrology*, **184**, pp. 261–276, 1996.
- 10. W. Zi-ting, An analytical solution for an exponential-type dispersion process, *Applied Mathematics and Mechanics*, **22**, pp. 368–371, 2001.
- 11. A. W. Warrick, J. W., Biggar, D. R. Nielsen, Simultaneous solute and water transfer for an unsaturated soil. *Water Resources Research*, 7, pp. 1216–1225, 1971.
- 12. D. A. Barry, G. Sposito, Analytical solution of a convection-dispersion model with time-dependent transport coefficients, *Water Resources Research*, **25**, pp. 2407–2416, 1989.
- 13. H. A. Basha, F. S. El-Habel, Analytical solution of the one-dimensional time-dependent transport equation, *Water Resources Research*, **29**, pp. 3209–3214 1993.
- 14. F. G. Blottner, Finite-difference method of solution of the boundary layer equations, *AIAA J.*, **8**, pp. 193–205, 1970.
- 15. O. O. Onyejekwe, A green element treatment of isothermal flow with second order reaction, *Int. Comm. Heat Mass Transfer*, **24**, pp. 251–264, 1997.
- U. Dale, Von Rosenberg Methods for the Solution of Partial Differential Equations, American Elsevier Publishing Company, Inc., New York, 1969.
- P. A. Ramachandran, Boundary integral solution method for axial-dispersion-with-reaction problems, *Chemical Engineering Journal*, 45, pp. 49–54, 1990.
- C. Zoppou, J.H. Knight, Comment on "A space-time accurate method for solving solute transport problems" by S. G. Li, F. Ruan and D. McLaughlin, *Water Resources Research*, 30, pp. 3233–3235, 1994.